

Trigonometry

ROBERT E. MOYER, PhD • FRANK AYERS, Jr. PhD

620 practice problems with step-by-step solutions

20 problem-solving videos online

Concise explanations of all course concepts



Use With These Courses:

Trigonometry, College Algebra and Trigonometry

Introductory Algebra and Trigonometry

Precalculus







This page intentionally left blank



Trigonometry

With Calculator-Based Solutions

Sixth Edition

Robert E. Moyer, PhD

Former Associate Professor of Mathematics Southwest Minnesota State University

Frank Ayres, Jr., PhD

Former Professor and Head, Department of Mathematics Dickinson College

Schaum's Outline Series



New York Chicago San Francisco Athens London Madrid Mexico City Milan New Delhi Singapore Sydney Toronto Copyright © 2018 by McGraw-Hill Education. All rights reserved. Except as permitted under the United States Copyright Act of 1976, no part of this publication may be reproduced or distributed in any form or by any means, or stored in a database or retrieval system, without the prior written permission of the publisher.

ISBN: 978-1-26-001149-4 MHID: 1-26-001149-6

The material in this eBook also appears in the print version of this title: ISBN: 978-1-26-001148-7, MHID: 1-26-001148-8.

eBook conversion by codeMantra Version 1.0

All trademarks are trademarks of their respective owners. Rather than put a trademark symbol after every occurrence of a trademarked name, we use names in an editorial fashion only, and to the benefit of the trademark owner, with no intention of infringement of the trademark. Where such designations appear in this book, they have been printed with initial caps.

McGraw-Hill Education eBooks are available at special quantity discounts to use as premiums and sales promotions or for use in corporate training programs. To contact a representative, please visit the Contact Us page at www.mhprofessional.com.

Dr. ROBERT E. MOYER taught mathematics and mathematics education at Southwest Minnesota State University in Marshall, Minnesota from 2002 to 2009 and served as an adjunct professor of mathematics there from 2009 to 2012. Before coming to SMSU, he taught mathematics and mathematics education at Fort Valley State University in Fort Valley, Georgia from 1985 to 2000. He served as head of the Department of Mathematics and Physics from 1992 to 1994.

Prior to teaching at the university level, Dr. Moyer served at the K-12 mathematics consultant for seven years at Middle Georgia Regional Educational Service Agency, a five-county education cooperative in central Georgia. Dr. Moyer taught high school mathematics for seven years in Rantoul, Illinois and for five years in Carmi, Illinois. He has developed and taught numerous inservice courses for mathematics teachers.

He received his Doctor of Philosophy in Mathematics Education from the University of Illinois (Urbana-Champaign) in 1974. He received his Master of Science in 1967 and his Bachelor of Science in 1964, both in Mathematics Education from Southern Illinois University (Carbondale).

The late **FRANK AYRES, JR.**, PhD, was formerly professor and head of the Department at Dickinson College, Carlisle, Pennsylvania. He is the author of eight Schaum's Outlines, including *Calculus, Differential Equations, 1st Year College Math, and Matrices.*

McGraw-Hill Education, the McGraw-Hill Education logo, Schaum's, and related trade dress are trademarks or registered trademarks of McGraw-Hill Education and/or its affiliates in the United States and other countries and may not be used without written permission. All other trademarks are the property of their respective owners. McGraw-Hill Education is not associated with any product or vendor mentioned in this book.

TERMS OF USE

This is a copyrighted work and McGraw-Hill Education and its licensors reserve all rights in and to the work. Use of this work is subject to these terms. Except as permitted under the Copyright Act of 1976 and the right to store and retrieve one copy of the work, you may not decompile, disassemble, reverse engineer, reproduce, modify, create derivative works based upon, transmit, distribute, disseminate, sell, publish or sublicense the work or any part of it without McGraw-Hill Education's prior consent. You may use the work for your own noncommercial and personal use; any other use of the work is strictly prohibited. Your right to use the work may be terminated if you fail to comply with these terms.

THE WORK IS PROVIDED "AS IS." McGRAW-HILL EDUCATION AND ITS LICENSORS MAKE NO GUARANTEES OR WARRANTIES AS TO THE ACCURACY, ADEQUACY OR COMPLETENESS OF OR RESULTS TO BE OBTAINED FROM USING THE WORK, INCLUDING ANY INFORMATION THAT CAN BE ACCESSED THROUGH THE WORK VIA HYPERLINK OR OTHERWISE, AND EXPRESSLY DISCLAIM ANY WARRANTY, EXPRESS OR IMPLIED, INCLUD-ING BUT NOT LIMITED TO IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE. McGraw-Hill Education and its licensors do not warrant or guarantee that the functions contained in the work will meet your requirements or that its operation will be uninterrupted or error free. Neither McGraw-Hill Education nor its licensors shall be liable to you or anyone else for any inaccuracy, error or omission, regardless of cause, in the work or for any damages resulting therefrom. McGraw-Hill Education has no responsibility for the content of any information accessed through the work. Under no circumstances shall McGraw-Hill Education and/or its licensors be liable for any indirect, incidental, special, punitive, consequential or similar damages that result from the use of or inability to use the work, even if any of them has been advised of the possibility of such damages. This limitation of liability shall apply to any claim or cause whatsoever whether such claim or cause arises in contract, tort or otherwise.

Preface

In revising the fifth edition, the strengths of the earlier editions were retained. There will still be the 20 online videos demonstrating the solution of some of the supplementary problems in the text. It is still possible to solve all the problems without the use of a calculator by using the tables provided, by using a basic scientific calculator, or by using a graphing calculator. The text is flexible enough to be used as a primary text for trigonometry, a supplement to a standard trigonometry text, or as a reference or review text for an individual student.

The book is complete in itself and can be used quite well by students studying trigonometry for the first time and by students needing to review the fundamental concepts and procedures of trigonometry. It is a helpful source finding a specific piece of trigonometric information needed in another course or on a job.

Each chapter contains a summary of the necessary definitions and theorems for a particular aspect of trigonometry followed by a set of solved problems. These solved problems include the proofs of theorems and the derivation of formulas. Each chapter ends with a set of supplementary problems with their answers.

Triangle solution problems, trigonometric identities, and trigonometric equations require a knowledge of elementary algebra and basic geometry. The problems have been carefully selected and their solutions spelled out in sufficient detail and arranged to illustrate clearly the algebraic processes involved as well as the use of the basic trigonometric relations.

ROBERT E. MOYER

This page intentionally left blank

Contents

| CHAPTER 1 | Angles and Applications | 1 |
|-----------|---|--|
| | 1.1 Introduction 1.2 Plane Angle 1.3 Measures of Angles 1.4 Arc Length 1.5 Lengths of Arcs on a Unit Circle 1.6 Area of a Sector 1.7 Linear and Angular Velocity Solved Problems Supplementary Problems | 1 1 2 3 4 5 5 6 8 |
| CHAPTER 2 | Trigonometric Functions of a General Angle | 10 |
| | 2.1 Coordinates on a Line 2.2 Coordinates in a Plane 2.3 Angles in Standard Position 2.4 Trigonometric Functions of a General Angle 2.5 Quadrant Signs of the Functions 2.6 Trigonometric Functions of Quadrantal Angle 2.7 Undefined Trigonometric Functions 2.8 Coordinates of Points on a Unit Circle 2.9 Circular Functions Solved Problems Supplementary Problems | 10 10 11 12 13 13 13 13 14 15 16 24 |
| CHAPTER 3 | Trigonometric Functions of an Acute Angle | |
| | 3.1 Trigonometric Functions of an Acute Angle 3.2 Trigonometric Functions of Complementary Angles 3.3 Trigonometric Functions of 30°, 45°, and 60° 3.4 Trigonometric Function Values 3.5 Accuracy of Results Using Approximations 3.6 Selecting the Function in Problem-Solving 3.7 Angles of Depression and Elevation Solved Problems Supplementary Problems | 26 27 27 28 28 29 30 30 30 |
| CHAPTER 4 | Solution of Right Triangles | 39 |
| | 4.1 Introduction 4.2 Four-Place Tables of Trigonometric Functions 4.3 Tables of Values of Trigonometric Functions 4.4 Using Tables to Find an Angle Given a Function Value | 39 39 39 41 |

| | 4.5 Calculator Values of Trigonometric Functions 4.6 Find an Angle Given a Function Value Using a Calculator 4.7 Accuracy in Computed Results Solved Problems Supplementary Problems | 42 43 44 44 50 | |
|-----------|--|----------------------------|--|
| CHAPTER 5 | Practical Applications | 53 | |
| | 5.1 Bearing | 53 | |
| | 5.2 Vectors | 54 | |
| | 5.3 Vector Addition | 54 | |
| | 5.4 Components of a Vector | 56 | |
| | 5.5 Air Navigation | 56 | |
| | 5.0 Inclined Plane | 57 | |
| | Solved Problems Supplementary Problems | 58 64 | |
| | | | |
| CHAPIER 6 | Reduction to Functions of Positive Acute Angles | 66 | |
| | 6.1 Coterminal Angles | 66 | |
| | 6.2 Functions of a Negative Angle | 66 | |
| | 6.3 Reference Angles | 67 | |
| | Solved Problems | 68 | |
| | Supplementary Problems | 73 | |
| CHAPTER 7 | Variations and Graphs of the Trigonometric Functions | 74 | |
| | 7.1 Line Representations of Trigonometric Functions | 74 | |
| | 7.2 Variations of Trigonometric Functions | 75 | |
| | 7.3 Graphs of Trigonometric Functions | 75 | |
| | 7.4 Horizontal and Vertical Shifts | 76 | |
| | 7.5 Periodic Functions | 77 | |
| | 7.6 Sine Curves | 77 | |
| | Solved Problems | 79 | |
| | Supplementary Problems | 82 | |
| CHAPTER 8 | Basic Relationships and Identities | 86 | |
| | 8.1 Basic Relationships | 86 | |
| | 8.2 Simplification of Trigonometric Expressions | 86 | |
| | 8.3 Trigonometric Identities | 87 | |
| | Solved Problems Supplementary Problems | 89 92 | |
| | | ,2 | |
| CHAPTER 9 | Trigonometric Functions of Two Angles | | |
| | 9.1 Addition Formulas | 94 | |
| | 9.2 Subtraction Formulas | 94 | |
| | 9.3 Double-Angle Formulas | 94 | |
| | 9.4 Hall-Angle Formulas | 95 | |
| | Supplementary Problems | 95 102 | |
| | Supplementary ribblems | 105 | |

| CHAPTER 10 | Sum, Difference, and Product Formulas | | 106 |
|------------|---------------------------------------|--|-----|
| | 10.1 | Products of Sines and Cosines | 106 |
| | 10.2 | Sum and Difference of Sines and Cosines | 106 |
| | | Solved Problems | 106 |
| | | Supplementary Problems | 108 |
| CHAPTER 11 | Obli | 110 | |
| | 11.1 | Oblique Triangles | 110 |
| | 11.2 | Law of Sines | 110 |
| | 11.3 | Law of Cosines | 110 |
| | 11.4 | Solution of Oblique Triangles | 111 |
| | | Solved Problems | 113 |
| | | Supplementary Problems | 126 |
| CHAPTER 12 | Area | a of a Triangle | 128 |
| | 12.1 | Area of a Triangle | 128 |
| | 12.2 | Area Formulas | 128 |
| | | Solved Problems | 129 |
| | | Supplementary Problems | 136 |
| CHAPTER 13 | Inverses of Trigonometric Functions | | 138 |
| | 13.1 | Inverse Trigonometric Relations | 138 |
| | 13.2 | Graphs of the Inverse Trigonometric Relations | 138 |
| | 13.3 | Inverse Trigonometric Functions | 138 |
| | 13.4 | Principal-Value Range | 140 |
| | 13.5 | General Values of Inverse Trigonometric Relations | 140 |
| | | Solved Problems | 140 |
| | | Supplementary Problems | 146 |
| CHAPTER 14 | Trigo | 147 | |
| | 14.1 | Trigonometric Equations | 147 |
| | 14.2 | Solving Trigonometric Equations | 147 |
| | | Solved Problems | 150 |
| | | Supplementary Problems | 154 |
| CHAPTER 15 | Com | 156 | |
| | 15.1 | Imaginary Numbers | 156 |
| | 15.2 | Complex Numbers | 156 |
| | 15.3 | Algebraic Operations | 156 |
| | 15.4 | Graphic Representation of Complex Numbers | 157 |
| | 15.5 | Graphic Representation of Addition and Subtraction | 157 |
| | 15.6 | Polar or Trigonometric Form of Complex Numbers | 157 |
| | 15.7 | Multiplication and Division in Polar Form | 159 |
| | 15.8 | De Moivre's Theorem | 159 |
| | 15.9 | Roots of Complex Numbers | 160 |
| | | Solved Problems | 161 |
| | | Supplementary Problems | 165 |

| APPENDIX 1 | Geometry | |
|------------|--|-----|
| | A1.1 Introduction | 168 |
| | A1.2 Angles | 168 |
| | A1.3 Lines | 169 |
| | A1.4 Triangles | 170 |
| | A1.5 Polygons | 171 |
| | A1.6 Circles | 172 |
| APPENDIX 2 | Tables | 173 |
| | Table 1 Trigonometric Functions—Angle in 10-Minute Intervals | 173 |
| | Table 2 Trigonometric Functions—Angle in Tenth of Degree Intervals | 181 |
| | Table 3 Trigonometric Functions—Angle in Hundredth of Radian Intervals | 193 |
| INDEX | | 199 |

Х





This page intentionally left blank



Angles and Applications

1.1 Introduction

Trigonometry is the branch of mathematics concerned with the measurement of the parts, sides, and angles of a triangle. **Plane trigonometry**, which is the topic of this book, is restricted to triangles lying in a plane. Trigonometry is based on certain ratios, called **trigonometric functions**, to be defined in the next chapter. The early applications of the trigonometric functions were to surveying, navigation, and engineering. These functions also play an important role in the study of all sorts of vibratory phenomena—sound, light, electricity, etc. As a consequence, a considerable portion of the subject matter is concerned with a study of the properties of and relations among the trigonometric functions.

1.2 Plane Angle

The plane angle *XOP*, Fig. 1.1, is formed by the two rays *OX* and *OP*. The point *O* is called the *vertex* and the half lines are called the *sides* of the angle.



More often, a plane angle is thought of as being generated by revolving a ray (in a plane) from the initial position OX to a terminal position OP. Then O is again the vertex, \overrightarrow{OX} is called the *initial side*, and \overrightarrow{OP} is called the *terminal side* of the angle.

An angle generated in this manner is called *positive* if the direction of rotation (indicated by a curved arrow) is counterclockwise and *negative* if the direction of rotation is clockwise. The angle is positive in Fig. 1.2(a) and (c) and negative in Fig. 1.2(b).



1.3 Measures of Angles

When an arc of a circle is in the interior of an angle of the circle and the arc joins the points of intersection of the sides of the angle and the circle, the arc is said to *subtend* the angle.

A *degree* (°) is defined as the measure of the central angle subtended by an arc of a circle equal to 1/360 of the circumference of the circle.

A minute (') is 1/60 of a degree; a second (") is 1/60 of a minute, or 1/3600 of a degree.

EXAMPLE 1.1 (a) $\frac{1}{4}(36^{\circ}24') = 9^{\circ}6'$ (b) $\frac{1}{2}(127^{\circ}24') = \frac{1}{2}(126^{\circ}84') = 63^{\circ}42'$ (c) $\frac{1}{2}(81^{\circ}15') = \frac{1}{2}(80^{\circ}75') = 40^{\circ}37.5'$ or $40^{\circ}37'30''$ (d) $\frac{1}{4}(74^{\circ}29'20'') = \frac{1}{4}(72^{\circ}149'20'') = \frac{1}{4}(72^{\circ}148'80'') = 18^{\circ}37'20''$

When changing angles in decimals to minutes and seconds, the general rule is that angles in tenths will be changed to the nearest minute and all other angles will be rounded to the nearest hundredth and then changed to the nearest second. When changing angles in minutes and seconds to decimals, the results in minutes are rounded to tenths and angles in seconds have the results rounded to hundredths.

EXAMPLE 1.2 (a) $62.4^{\circ} = 62^{\circ} + 0.4(60') = 62^{\circ}24'$ (b) $23.9^{\circ} = 23^{\circ} + 0.9(60') = 23^{\circ}54'$ (c) $29.23^{\circ} = 29^{\circ} + 0.23(60') = 29^{\circ}13.8' = 29^{\circ}13' + 0.8(60'')$ $= 29^{\circ}13'48''$ (d) $37.47^{\circ} = 37^{\circ} + 0.47(60') = 37^{\circ}28.2' = 37^{\circ}28' + 0.2(60'')$ $= 37^{\circ}28'12''$ (e) $78^{\circ}17' = 78^{\circ} + 17^{\circ}/60 = 78.28333...^{\circ} = 78.3^{\circ}$ (rounded to tenths) (f) $58^{\circ}22'16'' = 58^{\circ} + 22^{\circ}/60 + 16^{\circ}/3600 = 58.37111...^{\circ} = 58.37^{\circ}$ (rounded to hundredths)

A *radian* (rad) is defined as the measure of the central angle subtended by an arc of a circle equal to the radius of the circle. (See Fig. 1.3.)



The circumference of a circle = 2π (radius) and subtends an angle of 360°. Then 2π radians = 360°; therefore

1 radian =
$$\frac{180^{\circ}}{\pi}$$
 = 57.296° = 57°17′45′

1 degree =
$$\frac{\pi}{180}$$
 radian = 0.017453 rad

and

where $\pi = 3.14159$.

EXAMPLE 1.3 (a)
$$\frac{7}{12}\pi$$
 rad $=\frac{7\pi}{12} \cdot \frac{180^{\circ}}{\pi} = 105^{\circ}$
(b) $50^{\circ} = 50 \cdot \frac{\pi}{180}$ rad $=\frac{5\pi}{18}$ rad
(c) $-\frac{\pi}{6}$ rad $=-\frac{\pi}{6} \cdot \frac{180^{\circ}}{\pi} = -30^{\circ}$
(d) $-210^{\circ} = -210 \cdot \frac{\pi}{180}$ rad $=-\frac{7\pi}{6}$ rad

(See Probs. 1.1 and 1.2.)

1.4 **Arc Length**

On a circle of radius r, a central angle of θ radians, Fig. 1.4, intercepts an arc of length

 $s = r \theta$

that is, arc length = radius \times central angle in radians.

(NOTE: s and r may be measured in any convenient unit of length, but they must be expressed in the same unit.)



EXAMPLE 1.4 (a) On a circle of radius 30 in, the length of the arc intercepted by a central angle of $\frac{1}{3}$ rad is

$$s = r \theta = 30(\frac{1}{3}) = 10$$
 in

(b) On the same circle a central angle of 50° intercepts an arc of length

$$s = r \theta = 30 \left(\frac{5\pi}{18}\right) = \frac{25\pi}{3}$$
 in

(c) On the same circle an arc of length $1\frac{1}{2}$ ft subtends a central angle

 $\theta = \frac{s}{r} = \frac{18}{30} = \frac{3}{5}$ rad when s and r are expressed in inches or $\theta = \frac{s}{r} = \frac{3/2}{5/2} = \frac{3}{5}$ rad when s and r are expressed in feet

(See Probs. 1.3-1.8.)

1.5 Lengths of Arcs on a Unit Circle

The correspondence between points on a real number line and the points on a unit circle, $x^2 + y^2 = 1$, with its center at the origin is shown in Fig. 1.5.



The zero (0) on the number line is matched with the point (1, 0) as shown in Fig. 1.5(a). The positive real numbers are wrapped around the circle in a counterclockwise direction, Fig. 1.5(b), and the negative real numbers are wrapped around the circle in a clockwise direction, Fig. 1.5(c). Every point on the unit circle is matched with many real numbers, both positive and negative.

The radius of a unit circle has length 1. Therefore, the circumference of the circle, given by $2\pi r$, is 2π . The distance halfway around is π and the distance 1/4 the way around is $\pi/2$. Each positive number is paired with the length of an arc *s*, and since $s = r\theta = 1 \cdot \theta = \theta$, each real number is paired with an angle θ in radian measure. Likewise, each negative real number is paired with the negative of the length of an arc and, therefore, with a negative angle in radian measure. Figure 1.6(*a*) shows points corresponding to positive angles, and Fig. 1.6(*b*) shows points corresponding to negative angles.





Fig. 1.6

1.6 Area of a Sector

The area K of a sector of a circle (such as the shaded part of Fig. 1.7) with radius r and central angle θ radians is

$$K = \frac{1}{2}r^2\theta$$

that is, the area of a sector $=\frac{1}{2} \times$ the radius \times the radius \times the central angle in radians.

(NOTE: K will be measured in the square unit of area that corresponds to the length unit used to measure r.)



EXAMPLE 1.5 For a circle of radius 30 in, the area of a sector intercepted by a central angle of $\frac{1}{3}$ rad is

$$K = \frac{1}{2}r^2\theta = \frac{1}{2}(30)^2\left(\frac{1}{3}\right) = 150 \text{ in}^2$$

EXAMPLE 1.6 For a circle of radius 18 cm, the area of a sector intercepted by a central angle of 50° is

$$K = \frac{1}{2}r^2\theta = \frac{1}{2}(18)^2 \frac{5\pi}{18} = 45\pi \text{ cm}^2 \text{ or } 141 \text{ cm}^2 \text{ (rounded)}$$

(NOTE: $50^{\circ} = 5\pi/18 \text{ rad.}$)

(See Probs. 1.9 and 1.10.)

1.7 Linear and Angular Velocity

Consider an object traveling at a constant velocity along a circular arc of radius *r*. Let *s* be the length of the arc traveled in time *t*. Let 2 be the angle (in radian measure) corresponding to arc length *s*.

Linear velocity measures how fast the object travels. The linear velocity, *v*, of an object is computed by $\nu = \frac{arc \, length}{time} = \frac{s}{t}$.

Angular velocity measures how fast the angle changes. The angular velocity, ω (the lower-case Greek letter omega) of the object, is computed by $\omega = \frac{central angle in radians}{time} = \frac{\theta}{t}$.

The relationship between the linear velocity v and the angular velocity ω for an object with radius r is

 $v = r\omega$

where ω is measured in radians per unit of time and v is distance per unit of time.

(NOTE: v and ω use the same unit of time and r and v use the same linear unit.)

EXAMPLE 1.7 A bicycle with 20-in wheels is traveling down a road at 15 mi/h. Find the angular velocity of the wheel in revolutions per minute.

Because the radius is 10 in and the angular velocity is to be in revolutions per minute (r/min), change the linear velocity 15 mi/h to units of in/min.

$$v = 15 \frac{\text{mi}}{\text{h}} = \frac{15}{1} \frac{\text{mi}}{\text{h}} \cdot \frac{5280}{1} \frac{\text{ft}}{\text{mi}} \cdot \frac{12}{1} \frac{\text{in}}{\text{ft}} \cdot \frac{1}{60} \frac{\text{h}}{\text{min}} = 15,840 \frac{\text{in}}{\text{min}}$$
$$\omega = \frac{v}{r} = \frac{15,840}{10} \frac{\text{rad}}{\text{min}} = 1584 \frac{\text{rad}}{\text{min}}$$

To change ω to r/min, we multiply by $1/2\pi$ revolution per radian (r/rad).

$$\omega = 1584 \frac{\text{rad}}{\text{min}} = \frac{1584}{1} \frac{\text{rad}}{\text{min}} \cdot \frac{1}{2\pi} \frac{\text{r}}{\text{rad}} = \frac{792}{\pi} \frac{\text{r}}{\text{min}}$$
 or 252 r/min

EXAMPLE 1.8 A wheel that is drawn by a belt is making 1 revolution per second (r/s). If the wheel is 18 cm in diameter, what is the linear velocity of the belt in cm/s?

$$1\frac{\mathbf{r}}{\mathbf{s}} = \frac{1}{1} \cdot \frac{2\pi}{1} \frac{\mathrm{rad}}{\mathbf{r}} = 2\pi \mathrm{ rad/s}$$
$$v = r\omega = 9(2\pi) = 18\pi \mathrm{ cm/s} \quad \mathrm{or} \quad 57 \mathrm{ cm/s}$$

(See Probs. 1.11 to 1.15.)

SOLVED PROBLEMS

Use the directions for rounding stated on page 2.

- **1.1** Express each of the following angles in radian measure:
 - (a) 30° , (b) 135° , (c) $25^{\circ}30'$, (d) $42^{\circ}24'35''$, (e) 165.7° ,
 - (f) -3.85° , (g) -205° , (h) $-18^{\circ}30''$, (i) -0.21°
 - (a) $30^{\circ} = 30(\pi/180)$ rad $= \pi/6$ rad or 0.5236 rad
 - (b) $135^{\circ} = 135(\pi/180)$ rad $= 3\pi/4$ rad or 2.3562 rad
 - (c) $25^{\circ}30' = 25.5^{\circ} = 25.5(\pi/180)$ rad = 0.4451 rad
 - (d) $42^{\circ}24'35'' = 42.41^{\circ} = 42.41(\pi/180)$ rad = 0.7402 rad
 - (e) $165.7^{\circ} = 165.7(\pi/180)$ rad = 2.8920 rad
 - (f) $-3.85^\circ = -3.85(\pi/180)$ rad = -0.0672 rad
 - (g) $-205^{\circ} = (-205)(\pi/180)$ rad = -3.5779 rad
 - (h) $-18^{\circ}30'' = -18.01^{\circ} = (-18.01)(\pi/180)$ rad = -0.3143 rad
 - (i) $-0.21^{\circ} = (-0.21)(\pi/180)$ rad = -0.0037 rad

```
1.2 Express each of the following angles in degree measure:
```

(a) $\pi/3$ rad, (b) $5\pi/9$ rad, (c) 2/5 rad, (d) 4/3 rad, (e) $-\pi/8$ rad,

- (f) 2 rad, (g) 1.53 rad, (h) $-3\pi/20$ rad, (i) -7π rad
- (a) $\pi/3 \text{ rad} = (\pi/3)(180^{\circ}/\pi) = 60^{\circ}$
- (b) $5\pi/9 \text{ rad} = (5\pi/9)(180^{\circ}/\pi) = 100^{\circ}$
- (c) $2/5 \text{ rad} = (2/5)(180^{\circ}/\pi) = 72^{\circ}/\pi = 22.92^{\circ} \text{ or } 22^{\circ}55.2' \text{ or } 22^{\circ}55'12''$
- (d) $4/3 \text{ rad} = (4/3)(180^{\circ}/\pi) = 240^{\circ}/\pi = 76.39^{\circ} \text{ or } 76^{\circ}23.4' \text{ or } 76^{\circ}23'24''$
- (e) $-\pi/8 \text{ rad} = -(\pi/8)(180^{\circ}/\pi) = -22.5^{\circ} \text{ or } 22^{\circ}30'$
- (f) 2 rad = $(2)(180^{\circ}/\pi) = 114.59^{\circ}$ or $114^{\circ}35.4'$ or $114^{\circ}35'24''$
- (g) $1.53 \text{ rad} = (1.53)(180^{\circ}/\pi) = 87.66^{\circ} \text{ or } 87^{\circ}39.6' \text{ or } 87^{\circ}39'36''$
- (h) $-3\pi/20$ rad = $(-3\pi/20)(180^{\circ}/\pi) = -27^{\circ}$
- (i) -7π rad = $(-7\pi)(180^{\circ}/\pi) = -1260^{\circ}$

- **1.3** The minute hand of a clock is 12 cm long. How far does the tip of the hand move during 20 min? During 20 min the hand moves through an angle $\theta = 120^\circ = 2\pi/3$ rad and the tip of the hand moves over a distance $s = r\theta = 12(2\pi/3) = 8\pi$ cm = 25.1 cm.
- 1.4 A central angle of a circle of radius 30 cm intercepts an arc of 6 cm. Express the central angle θ in radians and in degrees.

$$\theta = \frac{s}{r} = \frac{6}{30} = \frac{1}{5}$$
 rad = 11.46°

1.5 A railroad curve is to be laid out on a circle. What radius should be used if the track is to change direction by 25° in a distance of 120 m?

We are finding the radius of a circle on which a central angle $\theta = 25^{\circ} = 5\pi/36$ rad intercepts an arc of 120 m. Then

$$r = \frac{s}{\theta} = \frac{12}{5\pi/36} = \frac{864}{\pi}$$
m = 275 m

1.6 A train is moving at the rate of 8 mi/h along a piece of circular track of radius 2500 ft. Through what angle does it turn in 1 min?

Since 8 mi/h = 8(5280)/60 ft/min = 704 ft/min, the train passes over an arc of length s = 704 ft in 1 min. Then $\theta = s/r = 704/2500 = 0.2816$ rad or 16.13°.

1.7 Assuming the earth to be a sphere of radius 3960 mi, find the distance of a point 36°N latitude from the equator.

Since $36^{\circ} = \pi/5$ rad, $s = r\theta = 3960(\pi/5) = 2488$ mi.

1.8 Two cities 270 mi apart lie on the same meridian. Find their difference in latitude.

$$\theta = \frac{s}{r} = \frac{270}{3960} = \frac{3}{44}$$
 rad or 3°54.4′

1.9 A sector of a circle has a central angle of 50° and an area of 605 cm². Find the radius of the circle. $K = \frac{1}{2}r^2\theta$; therefore $r = \sqrt{2K/\theta}$.

$$r = \sqrt{\frac{2K}{\theta}} = \sqrt{\frac{2(605)}{(5\pi/18)}} = \sqrt{\frac{4356}{\pi}} = \sqrt{1386.56}$$

= 37.2 cm

1.10 A sector of a circle has a central angle of 80° and a radius of 5 m. What is the area of the sector?

$$K = \frac{1}{2}r^2\theta = \frac{1}{2}(5)^2\left(\frac{4\pi}{9}\right) = \frac{50\pi}{9}m^2 = 17.5 m^2$$

1.11 A wheel is turning at the rate of 48 r/min. Express this angular speed in (a) r/s, (b) rad/min, and (c) rad/s.

(a)
$$48 \frac{r}{\min} = \frac{48}{1} \frac{r}{\min} \cdot \frac{1}{60} \frac{\min}{s} = \frac{4}{5} \frac{r}{s}$$

(b) $48 \frac{r}{\min} = \frac{48}{1} \frac{r}{\min} \cdot \frac{2\pi}{1} \frac{rad}{r} = 96\pi \frac{rad}{\min}$ or $301.6 \frac{rad}{\min}$
(c) $48 \frac{r}{\min} = \frac{48}{1} \frac{r}{\min} \cdot \frac{1}{60} \frac{\min}{s} \cdot \frac{2\pi}{1} \frac{rad}{r} = \frac{8\pi}{5} \frac{rad}{s}$ or $5.03 \frac{rad}{s}$

1.12 A wheel 4 ft in diameter is rotating at 80 r/min. Find the distance (in ft) traveled by a point on the rim in 1 s, that is, the linear velocity of the point (in ft/s).

$$80 \frac{\mathrm{r}}{\mathrm{min}} = 80 \left(\frac{2\pi}{60}\right) \frac{\mathrm{rad}}{\mathrm{s}} = \frac{8\pi}{3} \frac{\mathrm{rad}}{\mathrm{s}}$$

Then in 1 s the wheel turns through an angle $\theta = 8\pi/3$ rad and a point on the wheel will travel a distance $s = r \theta = 2(8\pi/3)$ ft = 16.8 ft. The linear velocity is 16.8 ft/s.

1.13 Find the diameter of a pulley which is driven at 360 r/min by a belt moving at 40 ft/s.

$$360 \frac{\mathrm{r}}{\mathrm{min}} = 360 \left(\frac{2\pi}{60}\right) \frac{\mathrm{rad}}{\mathrm{s}} = 12\pi \frac{\mathrm{rad}}{\mathrm{s}}$$

Then in 1 s the pulley turns through an angle $\theta = 12\pi$ rad and a point on the rim travels a distance s = 40 ft.

$$d = 2r = 2\left(\frac{s}{\theta}\right) = 2\left(\frac{40}{12\pi}\right)$$
ft $= \frac{20}{3\pi}$ ft $= 2.12$ ft

1.14 A point on the rim of a turbine wheel of diameter 10 ft moves with a linear speed of 45 ft/s. Find the rate at which the wheel turns (angular speed) in rad/s and in r/s.

In 1 s a point on the rim travels a distance s = 45 ft. Then in 1 s the wheel turns through an angle $\theta = s/r = 45/5 = 9$ rad and its angular speed is 9 rad/s.

Since $1 r = 2\pi$ rad or 1 rad $= 1/2\pi$ r, 9 rad/s $= 9(1/2\pi)$ r/s = 1.43 r/s.

1.15 Determine the speed of the earth (in mi/s) in its course around the sun. Assume the earth's orbit to be a circle of radius 93,000,000 mi and 1 year = 365 days.

In 365 days the earth travels a distance of $2\pi r = 2(3.14)(93,000,000)$ mi.

In 1 s it will travel a distance $s = \frac{2(3.14)(93,000,000)}{365(24)(60)(60)}$ mi = 18.5 mi. Its speed is 18.5 mi/s.

SUPPLEMENTARY PROBLEMS

Use the directions for rounding stated on page 2.

1.16 Express each of the following in radian measure:

(a) 25° , (b) 160° , (c) $75^{\circ}30'$, (d) $112^{\circ}40'$, (e) $12^{\circ}12'20''$, (f) 18.34° *Ans.* (a) $5\pi/36$ or 0.4363 rad (c) $151\pi/360$ or 1.3177 rad (e) 0.2130 rad (b) $8\pi/9$ or 2.7925 rad (d) $169\pi/270$ or 1.9664 rad (f) 0.3201 rad

1.17 Express each of the following in degree measure:

(a) $\pi/4$ rad, (b) $7\pi/10$ rad, (c) $5\pi/6$ rad, (d) 1/4 rad, (e) 7/5 rad

Ans. (a) 45° , (b) 126° , (c) 150° , (d) $14^{\circ}19'12''$ or 14.32° , (e) $80^{\circ}12'26''$ or 80.21°

1.18 On a circle of radius 24 in, find the length of arc subtended by a central angle of (a) 2/3 rad, (b) $3\pi/5$ rad, (c) 75° , (d) 130° .

Ans. (a) 16 in, (b) 14.4π or 45.2 in, (c) 10π or 31.4 in, (d) $52\pi/3$ or 54.4 in

1.19 A circle has a radius of 30 in. How many radians are there in an angle at the center subtended by an arc of (a) 30 in, (b) 20 in, (c) 50 in?

Ans. (a) 1 rad, (b) $\frac{2}{3}$ rad, (c) $\frac{5}{3}$ rad

1.20 Find the radius of the circle for which an arc 15 in long subtends an angle of (a) 1 rad, (b) ²/₃ rad, (c) 3 rad, (d) 20°, (e) 50°.

Ans. (a) 15 in, (b) 22.5 in, (c) 5 in, (d) 43.0 in, (e) 17.2 in

- **1.21** The end of a 40-in pendulum describes an arc of 5 in. Through what angle does the pendulum swing? Ans. $\frac{1}{8}$ rad or 7°9′36″ or 7.16°
- **1.22** A train is traveling at the rate 12 mi/h on a curve of radius 3000 ft. Through what angle has it turned in 1 min? *Ans.* 0.352 rad or 20°10′ or 20.17°
- **1.23** A curve on a railroad track consists of two circular arcs that make an S shape. The central angle of one is 20° with radius 2500 ft and the central angle of the other is 25° with radius 3000 ft. Find the total length of the two arcs. *Ans.* $6250\pi/9$ or 2182 ft
- **1.24** Find the area of the sector determined by a central angle of $\pi/3$ rad in a circle of diameter 32 mm. Ans. 128 $\pi/3$ or 134.04 mm²
- **1.25** Find the central angle necessary to form a sector of area 14.6 cm² in a circle of radius 4.85 cm. Ans. 1.24 rad or 71.05° or $71^{\circ}3'$
- **1.26** Find the area of the sector determined by a central angle of 100° in a circle with radius 12 cm. Ans. 40π or 125.7 cm²
- **1.27** If the area of a sector of a circle is 248 m² and the central angle is 135° , find the diameter of the circle. *Ans.* diameter = 29.0 m
- **1.28** A flywheel of radius 10 cm is turning at the rate 900 r/min. How fast does a point on the rim travel in m/s? *Ans.* 3π or 9.4 m/s
- **1.29** An automobile tire has a diameter of 30 in. How fast (r/min) does the wheel turn on the axle when the automobile maintains a speed of 45 mi/h?

Ans. 504 r/min

- **1.30** In grinding certain tools the linear velocity of the grinding surface should not exceed 6000 ft/s. Find the maximum number of revolutions per second of (a) a 12-in (diameter) emery wheel and (b) an 8-in wheel.
 - Ans. (a) $6000/\pi$ r/s or 1910 r/s, (b) $9000/\pi$ r/s or 2865 r/s
- 1.31 If an automobile wheel 78 cm in diameter rotates at 600 r/min, what is the speed of the car in km/h?Ans. 88.2 km/h